



# Validation of Satellite Sounder Environmental Data Records: Application to S-NPP

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**2014 AMS Annual Meeting**

Atlanta, Georgia, USA

6 February 2014

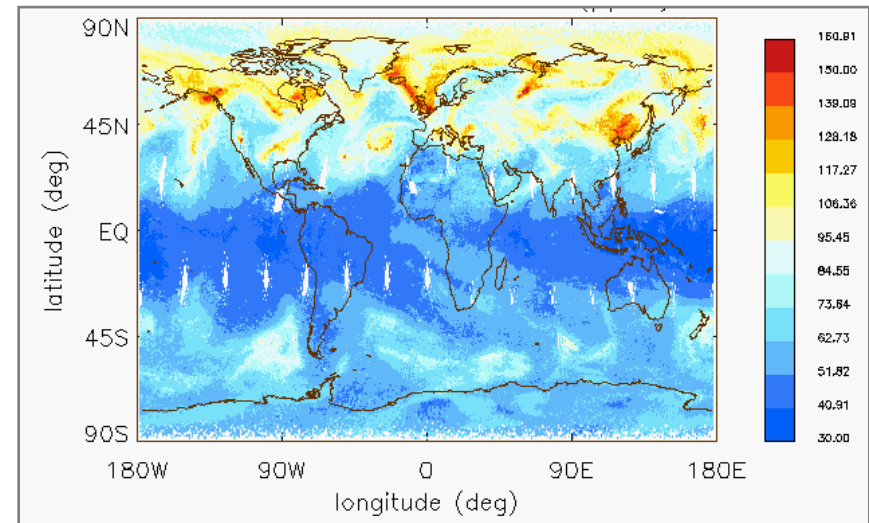
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# Introduction: JPSS CrIMSS

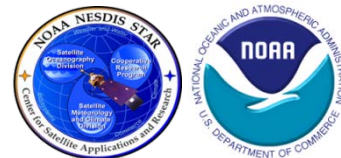


- **Joint Polar Satellite System (JPSS) Cross-track Infrared Microwave Sounder Suite (CrIMSS) sounder system:**
  - **Cross-track Infrared Sounder (CrIS) and Advanced Technology Microwave Sounder (ATMS)**
  - Designed to retrieve **atmospheric vertical temperature and moisture profiles (AVTP and AVMP)**, with optimal vertical resolution under **non-precipitating conditions** (cloudy, partly cloudy and clear)
- **CrIMSS Operational EDR Algorithms**
  - **NOAA Unique CrIS/ATMS Processing System (NUCAPS)**
    - Exact line-for-line modular implementation of the iterative, multistep AIRS Science Team retrieval algorithm
    - AVTP, AVMP and trace gas profiles ( $O_3$ ,  $CO$ ,  $CO_2$ ,  $CH_4$ , etc.; e.g., see [16ATCHEM Oral 5.3, Smith and Nalli](#))
    - See [10GOESRJPSS Oral 9.1 \(Gambacorta et al.\)](#)
  - Original IDPS Algorithm
    - Optimal Estimation (OE) algorithm originally developed by AER
    - See [10GOESRJPSS Poster 353 \(Divakarla et al.\)](#)

## NUCAPS Ozone retrieval 450 hPa 15 May 2013



# The Importance of Validating Sounder EDRs



- **Validation** is “the process of ascribing uncertainties to these radiances and retrieved quantities through comparison with correlative observations” (*Fetzer et al.*, 2003).
- Validation of EDRs provides implicit validation of SDRs
- Includes validation of retrieved cloud-cleared radiances (CCRs), which are known to have positive impact on NWP (e.g., *Le Marshall et al.*, 2008)
- Enables development/improvement of algorithms
- Sounder EDR (AVTP, AVMP and trace gas) users include
  - WFOs (AWIPS)
  - Science users/investigators (e.g., *Pagano et al.*, 2013)

# JPSS Cal/Val Program



- **JPSS Cal/Val Phases**
  - Pre-Launch / Early Orbit Checkout (EOC)
  - **Intensive Cal/Val (ICV)**
    - Validation of EDRs against multiple correlative datasets
  - **Long-Term Monitoring (LTM)**
    - Characterization of all EDR products and long-term demonstration of performance
  
- In accordance with the JPSS phased schedule, the **S-NPP CrIMSS EDR cal/val plan** was devised to ensure the EDR would meet the mission Level 1 requirements (*Barnet, 2009*)
  
- The **EDR validation methodology** draws upon previous work with AIRS and IASI and is summarized in this talk (after *Nalli et al., 2013b*)

Atmospheric Vertical Temperature Profile (AVTP) Measurement Uncertainty – Layer Average Temperature Error	
PARAMETER	THRESHOLD
AVTP Clear, surface to 300 mb	1.6 K / 1-km layer
AVTP Clear, 300 to 30 mb	1.5 K / 3-km layer
AVTP Clear, 30 mb to 1 mb	1.5 K / 5-km layer
AVTP Clear, 1 mb to 0.5 mb	3.5 K / 5-km layer
AVTP Cloudy, surface to 700 mb	2.5 K / 1-km layer
AVTP Cloudy, 700 mb to 300 mb	1.5 K / 1-km layer
AVTP Cloudy, 300 mb to 30 mb	1.5 K / 3-km layer
AVTP Cloudy, 30 mb to 1 mb	1.5 K / 5-km layer
AVTP Cloudy, 1 mb to 0.5 mb	3.5 K / 5-km layer

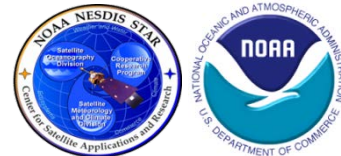
Atmospheric Vertical Moisture Profile (AVMP) Measurement Uncertainty – 2-km Layer Average Mixing Ratio % Error	
PARAMETER	THRESHOLD
AVMP Clear, surface to 600 mb	Greater of 20% or 0.2 g/kg / 2-km layer
AVMP Clear, 600 to 300 mb	Greater of 35% or 0.1 g/kg / 2-km layer
AVMP Clear, 300 to 100 mb	Greater of 35% or 0.1 g/kg / 2-km layer
AVMP Cloudy, surface to 600 mb	Greater of 20% of 0.2 g/kg / 2-km layer
AVMP Cloudy, 600 mb to 400 mb	Greater of 40% or 0.1 g/kg / 2-km layer
AVMP Cloudy, 400 mb to 100 mb	Greater of 40% or 0.1 g/kg / 2-km layer



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# VALIDATION METHODOLOGY

# Validation Methodology Hierarchy (1/2)



## 1. Numerical Model (e.g., ECMWF, NCEP/GFS) Global Comparisons

- Large, global samples acquired from Focus Days
- Useful for early sanity checks, bias tuning and regression
- However, not independent truth data

## 2. Satellite EDR (e.g., AIRS, ATOVS, COSMIC) Intercomparisons

- Global samples acquired from Focus Days (e.g., AIRS)
- Consistency checks; merits of different retrieval algorithms
- However, IR sounders have similar error characteristics; must take rigorous account of averaging kernels of both systems (e.g., *Rodgers and Connor, 2003*)

## 3. Conventional RAOB Matchup Assessments

- Conventional WMO/GTS operational sondes launched ~2/day for NWP (e.g., NPROVS)
- Useful for representation of global zones and long-term monitoring
- Large statistical samples acquired after a couple months' accumulation
- Limitations:
  - Skewed distribution toward NH-continental sites
  - Significant mismatch errors
  - Non-uniform, less-accurate and poorly characterized radiosonde types used in data sample

# Validation Methodology Hierarchy (2/2)



## 4. Dedicated/Reference RAOB Matchup Assessments

- Dedicated sondes: Vaisala RS92-SGP dedicated for the purpose of satellite validation
  - Well-specified error characteristics and optimal accuracy
  - Minimal mismatch errors
  - Include atmospheric state “best estimates” or “merged soundings”
- Reference sondes: CFH, corrected RS92, Vaisala RR01 under development
  - Traceable measurement
- Detailed performance specification and regional characterization
- Limitation: Small sample sizes and geographic coverage
- E.g., ARM sites (e.g., *Tobin et al.*, 2006), ideally GRUAN

## 5. Intensive Field Campaign *Dissections*

- Include dedicated RAOBs, especially those *not* assimilated into NWP models
- Include ancillary datasets (e.g., ozonesondes, lidar, M-AERI, MWR, sunphotometer, etc.)
- Ideally include funded aircraft campaign using aircraft IR sounder (e.g., NAST-I, S-HIS) underflights ([See 10GOESRJPSS Poster 690, Taylor et al.](#))
- Detailed performance specification; state specification; SDR cal/val; EDR “dissections”
- E.g., AEROSE, JAIVEX, WAVES, AWEX-G, EAQUATE





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# ASSESSMENT METHODOLOGY

# Assessment Methodology: Reducing Truth to Correlative Layers



- The relationship between the forward and inverse problem (*Rodgers, 1990*) requires that high-resolution truth measurements (e.g., dedicated RAOB) should be reduced to correlative RTA layers

$$\hat{\mathbf{x}} = I[F(\mathbf{x}, \mathbf{b}), \mathbf{b}, \mathbf{c}]$$

- Basic approach is to integrate quantities over the atmospheric path (e.g., number densities  $\rightarrow$  column abundances), interpolate to RTA (arbitrary) levels, then compute then RTA layer quantities

$$\Sigma_x(z) = \int_{z_t}^z N_x(z') dz'$$

# Assessment Methodology: Statistical Metrics



- Level 1 AVTP and AVMP accuracy requirements are defined over **coarse layers**, roughly 1–5 km for tropospheric AVTP and 2 km for AVMP (Table, Slide 5).

## AVTP

$$\text{RMS}(\Delta T_{\mathcal{L}}) = \sqrt{\frac{1}{n_j} \sum_{j=1}^{n_j} (\Delta T_{\mathcal{L},j})^2} \quad \text{BIAS}(\Delta T_{\mathcal{L}}) \equiv \overline{\Delta T_{\mathcal{L}}} = \frac{1}{n_j} \sum_{j=1}^{n_j} \Delta T_{\mathcal{L},j}$$

$$\text{STD}(\Delta T_{\mathcal{L}}) \equiv \sigma(\Delta T_{\mathcal{L}}) = \sqrt{[\text{RMS}(\Delta T_{\mathcal{L}})]^2 - [\text{BIAS}(\Delta T_{\mathcal{L}})]^2}$$

## AVMP and O<sub>3</sub>

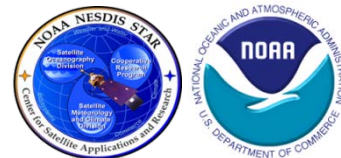
- W2 weighting was used in determining Level 1 Requirements
- To allow compatible STD calculation, W2 weighting should be consistently used for both RMS and BIAS

$$\text{RMS}(\Delta q_{\mathcal{L}}) = \sqrt{\frac{\sum_{j=1}^{n_j} W_{\mathcal{L},j} (\Delta q_{\mathcal{L},j})^2}{\sum_{j=1}^{n_j} W_{\mathcal{L},j}}}, \quad \text{water vapor weighting factor, } W_{\mathcal{L},j},$$

$$\text{BIAS}(\Delta q_{\mathcal{L}}) = \frac{\sum_{j=1}^{n_j} W_{\mathcal{L},j} \Delta q_{\mathcal{L},j}}{\sum_{j=1}^{n_j} W_{\mathcal{L},j}}, \quad W_{\mathcal{L},j} = \begin{cases} 1 & , W^0 \\ q_{\mathcal{L},j} & , W^1 \\ (q_{\mathcal{L},j})^2 & , W^2 \end{cases}$$

$$\text{STD}(\Delta q_{\mathcal{L}}) = \sqrt{[\text{RMS}(\Delta q_{\mathcal{L}})]^2 - [\text{BIAS}(\Delta q_{\mathcal{L}})]^2}$$

# Assessment Methodology: Use of Averaging Kernels (AKs)



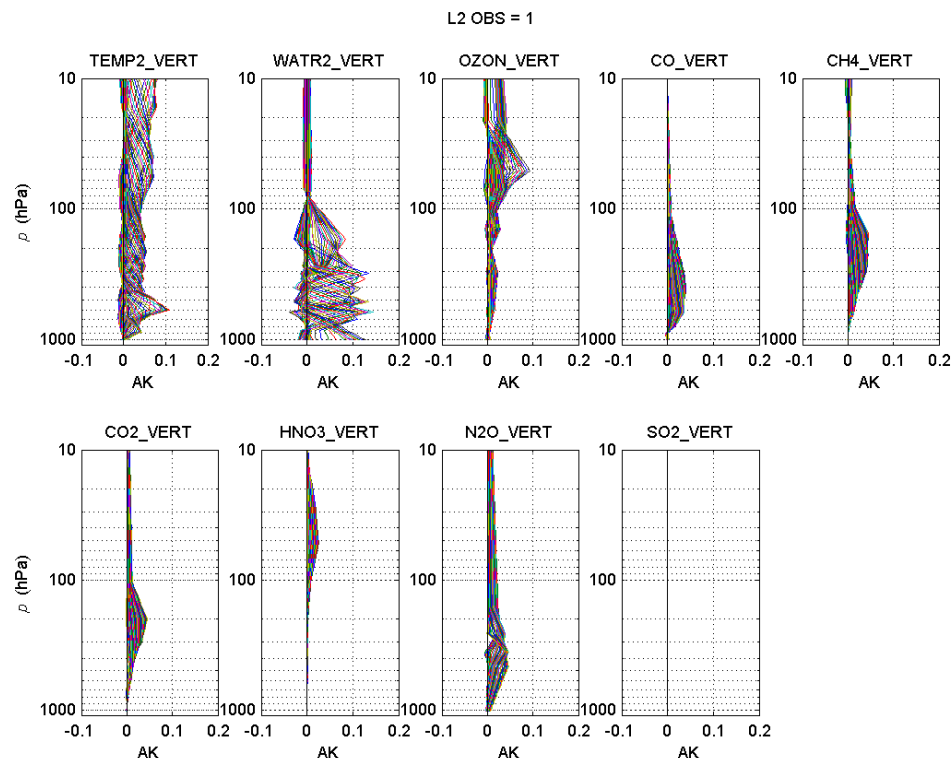
- **AKs** define the **vertical sensitivity** of the sounder measurement system

$$\mathbf{A} \equiv \frac{\partial \hat{\mathbf{x}}}{\partial \mathbf{x}}$$

- Facilitates intercomparisons of profiles obtained by two different observing systems
- Retrieval AKs can be used to “smooth” correlative truth (RAOBs reduced to RTA layers), thereby **removing null-space errors** otherwise present

$$\mathbf{x}_s = \mathbf{A}(\mathbf{x} - \mathbf{x}_0) + \mathbf{x}_0$$

## NOAA-Unique IASI Averaging Kernels





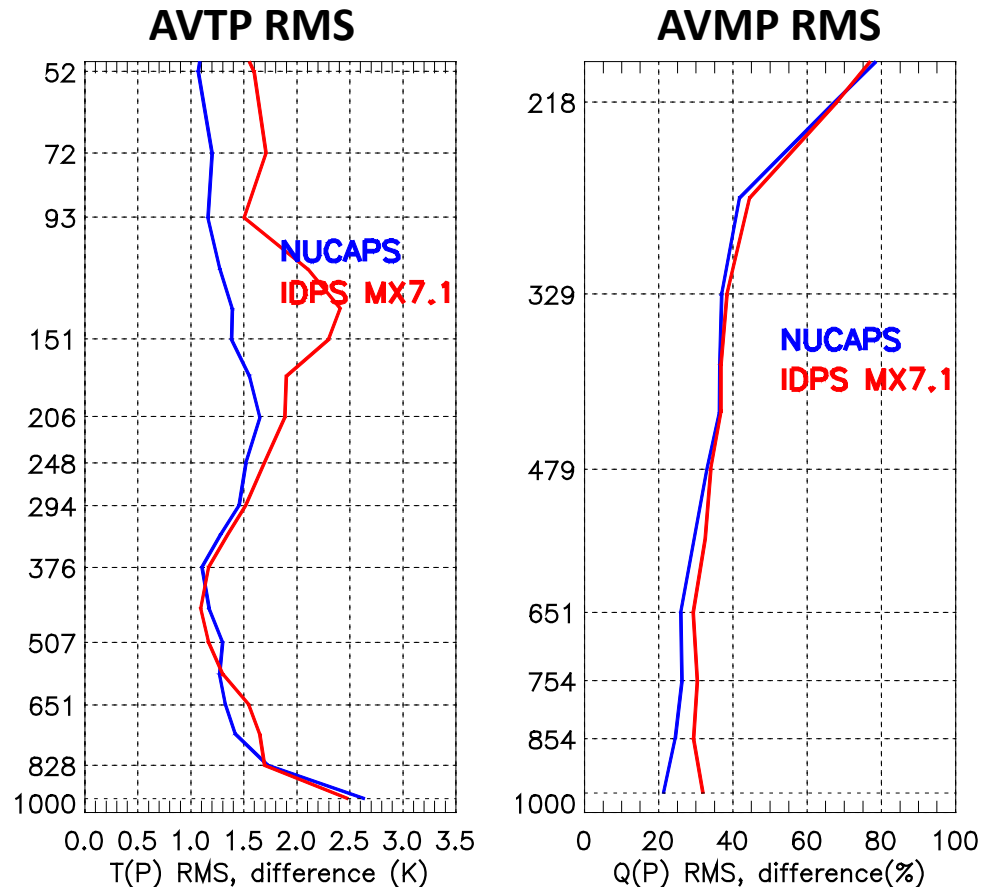
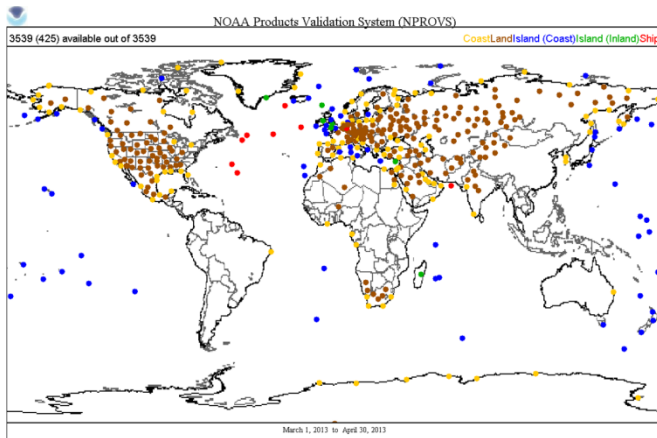
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# APPLICATION TO S-NPP

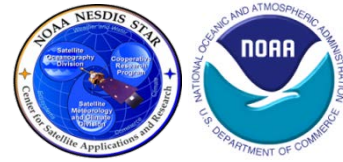
# Conventional RAOB Matchups



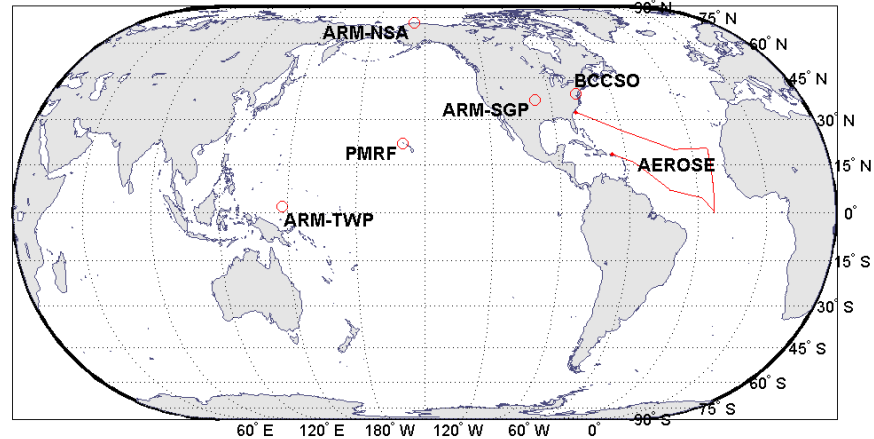
- **NOAA Products Validation System (NPROVS) (Reale et al., 2012)**
  - See 10GOESRJPSS Posters 675 (Sun et al.) and 677 (Petty et al.)
- Matchup Sample Jul-Dec 2013,  $N = 34234$



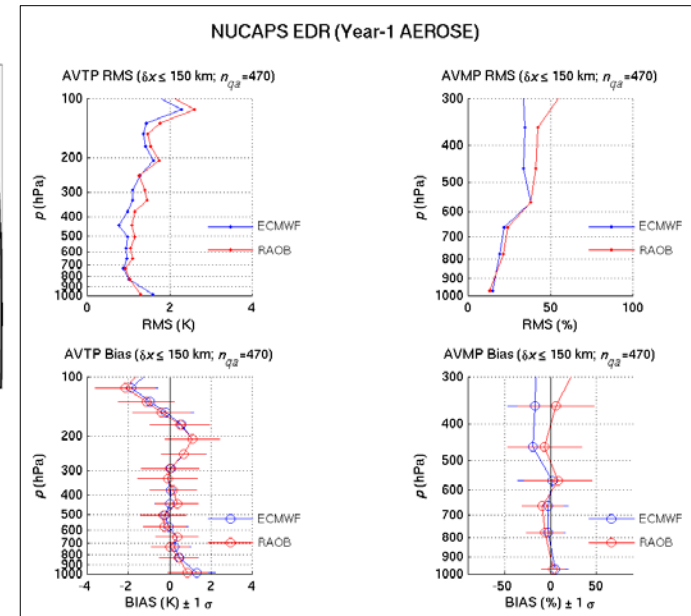
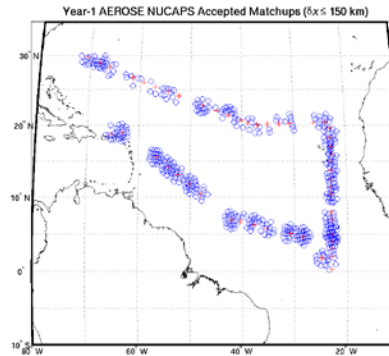
# JPSS S-NPP Dedicated RAOBs



S-NPP CrIMSS EDR ICV Dedicated RAOB Sites (Year 1)



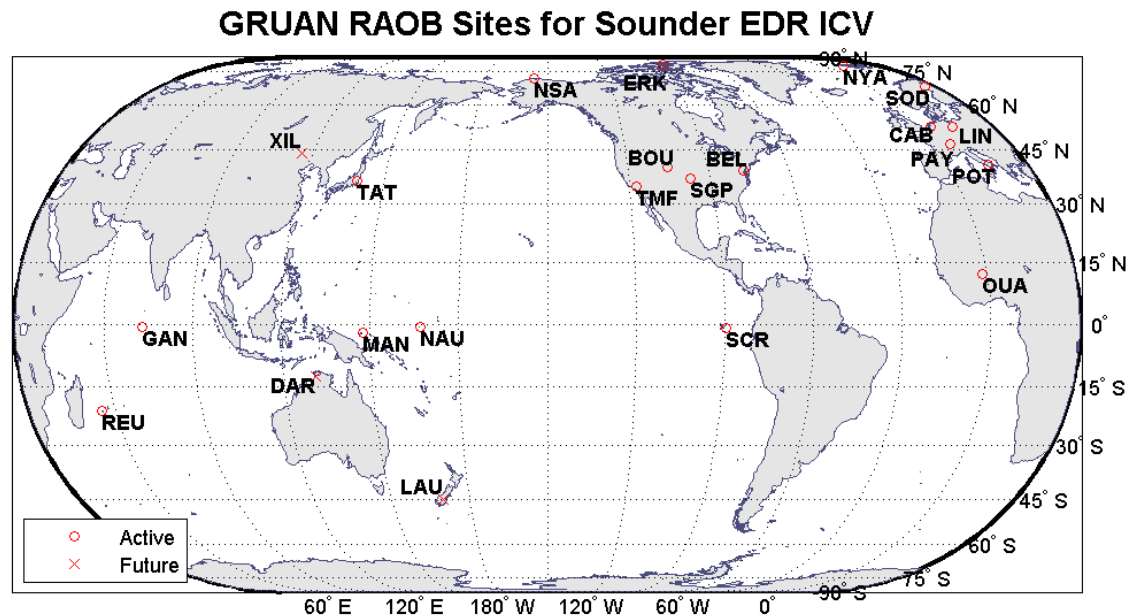
- **PMRF** (Kauai, Hawaii)
  - 2012 SNPP testbed site
- **BCCSO** (Beltsville, MD)
  - Howard University
  - continent, urban
- **ARM Sites**
  - TWP (Manus Island)
  - SGP (Oklahoma)
  - NSA (Alaska)
  - See 10GOESRJPSS Poster 700 (*Borg et al.*)
- **AEROSE Campaigns**
  - Tropical Atlantic Ocean
  - See 10GOESRJPSS Poster 681 (*Nalli et al.*)



# Reference RAOBs

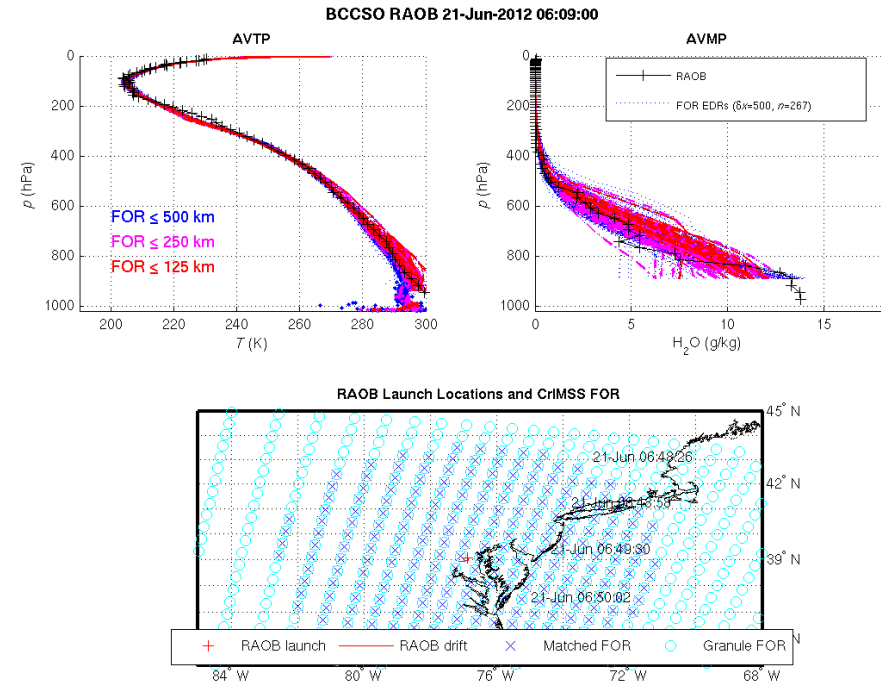
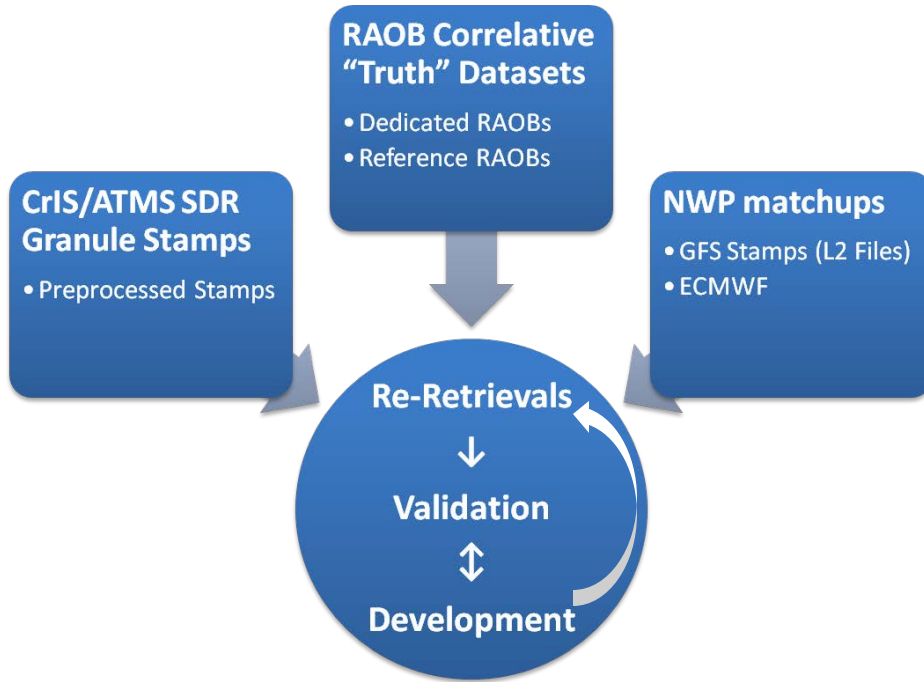
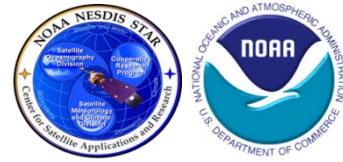


- GRUAN reference RAOB matchups with S-NPP are currently being acquired via the **NPROVS+** system
  - Traceable measurements
  - See [10GOESRJPSS Poster 675 \(Reale et al.\)](#)





# STAR Validation Archive (VALAR)



- A VALAR “stamp” is roughly defined as a granule-level input file (matched with a RAOB anchor point) needed for performing re-retrievals
- SDR stamps consist of 4-scan line granules within  $\pm 1$  minute of overpass,  $\approx 500$  km radius

- **SNPP CrIMSS NUCAPS Stages 1-3 Validated Maturities**
  - NUCAPS Phase II algorithm improvements
- **Long Term Monitoring (LTM) of S-NPP CrIMSS**
  - Apply averaging kernels in NUCAPS error analyses
  - Ensemble statistics versus GRUAN and dedicated RAOB
  - calc – obs (e.g., CCR) analyses (e.g., *Nalli et al.*, 2013a)
  - NUCAPS trace gas profile validation (e.g., O<sub>3</sub>, CO, etc.)
  - NUCAPS skin SST validation
  - NUCAPS EDR algorithm development (e.g., AVTP/AVMP uncertainty estimates)

# Acknowledgments



- The **NOAA Joint Polar Satellite System Office Office** (M. D. Goldberg) and the former Integrated Program Office (IPO)
- The STAR Satellite Meteorology and Climatology Division (F. Weng and I. Csiszar).
- AEROSE works in collaboration with the NOAA PIRATA Northeast Extension (PNE) project and is supported by the NOAA Educational Partnership Program grant NA17AE1625, NOAA grant NA17AE1623, JPSS and NOAA/NESDIS/STAR.
- Contributors to the S-NPP CrIMSS EDR validation effort: L. Zhou, M. Wilson, F. Iturbide-Sanchez, C. Tan, X. Xiong, H. Xie, F. Tilley, C. Brown, M. Petty (NOAA/NESDIS/STAR), and M. Feltz (UW/CIMSS).
- Contributions to the S-NPP validation data collection effort: B. Demoz and M. Oyola (Howard University); D. Wolfe (NOAA/ESRL); J. E. Wessel (Aerospace)
- D. Holdridge and J. Mather and the U.S. DOE ARM Climate Research Facility for its support of the satellite overpass radiosonde efforts.